

# Anish Madan



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








## RESEARCH INTERESTS

- 3D Vision
- Foundational Models
- Digital Twins
- Vision for Robotics




## EDUCATION

- **Carnegie Mellon University (CMU)** Pittsburgh, USA  
*Masters of Science, Robotics; CGPA: 4.09/4.00*  
Aug 2022 - Aug 2024  
Advisor: [Prof. Deva Ramanan](#)
- **Indraprastha Institute of Information Technology (IIIT), Delhi** India  
*B.Tech, Computer Science and Applied Maths; CGPA: 8.78/10.00*  
Aug 2016 - Jan 2021  
Advisor: [Prof. Saket Anand](#)

## CONFERENCE PUBLICATIONS

- SMORE: Simultaneous Map and Object Reconstruction** 3DV 2025  
*N. Chodosh\*, A. Madan\*, S. Lucey, D. Ramanan.*  
Webpage , Paper 
- Revisiting Few-Shot Object Detection with Vision-Language Models** NeurIPS D&B 2024  
*A. Madan\*, N. Peri\*, S. Kong, D. Ramanan.*  
Paper , Code 
- SLI-pSp: Injecting Multi-Scale Spatial Layout in pSp** WACV 2023  
*AN Mathur\*, A. Madan\*, O. Sharma*  
Paper 
- REGroup: Rank-aggregating Ensemble of Generative Classifiers for Robust Predictions** WACV 2022  
*L. Tiwari, A. Madan, S. Anand, and S. Banerjee*  
Paper , Code 
- B-SMALL: A Bayesian Neural Network approach to Sparse MAML** ICASSP 2021  
*A. Madan, R. Prasad.*  
Paper , Code 
- Category Consistent Cyclic Visual Question Generation** MMAsia 2020  
*S. Uppal\*, A. Madan\*, S. Bhagat\*, Y. Yu, R. Shah.*  
Paper , Code 

## WORKSHOP CHALLENGES AND PUBLICATIONS

- Foundational FSOD Challenge** VPLOW @ CVPR 2024  
*A. Madan\*, N. Peri\*, S. Kong, D. Ramanan*  
Paper , Challenge 
- NurtureNet: A Multi-task Video-based Approach for Newborn Anthropometry** CVPM @ CVPR 2024  
*Y. Khandelwal, ..., A. Madan, ..., M. Tapaswi*  
Paper 

\* Equal Contribution

## ACADEMIC EXPERIENCE

- **CMU Center for Autonomous Vehicle Research | CMU** Pittsburgh, USA  
*Graduate Research Assistant | Advisor: Prof. Deva Ramanan | NeurIPS '24, 3DV '25*  
Oct 2022 - Present
  - Scalable Approach for Creating Digital Twins using LiDAR**
    - Developed **SMORE**: a space-time reconstruction technique for urban scenes using LiDAR
    - Demonstrated **10x** improvement in **LiDAR Novel View Synthesis** over SOTA
    - Achieved precise reconstruction of static and dynamic objects, enabling **high-quality depth map synthesis**
    - Currently, leading efforts to extend SMORE to support multiple modalities (RGB and LiDAR)
  - Foundation Model Priors for High-Quality Annotations**
    - Reformulated Few-Shot Object Detection (FSOD) as alignment of Foundational Vision-Language Models (VLMs) to multi-modal annotator instructions
    - Proposed **Foundational FSOD**: a new **benchmark** on nuImages, a popular Autonomous Vehicles dataset
    - Released a **CVPR '24 Challenge** and filed a patent based on this work (*under review*)
- **Graphics Research Group | IIIT-Delhi** New Delhi, India  
*Research Intern | Advisor: Dr. Ojaswa Sharma | WACV '23*  
Jan 2021 - July 2022

- Proposed a StyleGAN based Image-to-Image Translation model to explicitly capture fine-grained semantics and structures in addition to the global style.
- Improved FID performance by 16 points over SOTA on CelebA (Label-to-Face generation).
- **Bayesian View of Meta-Learning | IIIT-Delhi** New Delhi, India  
*Undergraduate Researcher / Advisor: Dr. Ranjitha Prasad / ICASSP '21* Jan 2020 - Jan 2021
  - Proposed a Bayesian neural network based approach to MAML to alleviate the problem of overfitting by introducing network sparsity.
- **Infosys Center of Artificial Intelligence | IIIT-Delhi** New Delhi, India  
*B.Tech Thesis / Advisor: Dr. Saket Anand / WACV '22* Aug 2018 - Feb 2020
  - Developed a novel adversarial defense technique to secure Deep Neural Networks against adversarial attacks.
  - Benchmarked on ImageNet and demonstrated performance at-par with SOTA whilst requiring only a fraction of the data.

## INDUSTRY EXPERIENCE

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- **Bosch Research** Pittsburgh, USA  
*Machine Learning Research Intern* May 2024 - Aug 2024
  - Setup automatic depth rendering pipeline using LiDAR reconstructions from SMORE
  - Achieved higher quality **depth synthesis from extreme viewpoints** when compared to **NeRF**-based SOTA
- **Wadhvani AI** New Delhi, India  
*Associate ML Scientist / Advisor: Dr. Makarand Tapaswi* Jan 2021 - July 2022
  - **Newborn Anthropometry Project:** Developed 3D mesh reconstruction based (SMPL, HMR) and parametric model-free (Contrastive Learning, Transformers) techniques to analyse low-birth weight babies from a video.
  - Contributed in developing a dataset of baby keypoints and joints.
    - \* Conducted annotation training exercises with external agencies.
- **Robert Bosch Research and Technology Centre** Bangalore, India  
*Research Intern* Aug 2019 - Dec 2019
  - Developed context-based *cut-and-paste* data augmentation techniques for semantic segmentation.
  - Improved performance by 5 AP on various categories, e.g., pedestrians on Bosch's Autonomous Vehicle dataset.
- **IIIT-D Autonomous Last mile VEHICLE (ALIVE)** New Delhi, India  
*Summer Intern / Advisor: Dr. Saket Anand* May 2018 - July 2018
  - Developed methods to detect speed breakers for AVs and improved existing lane detection algorithms.

## REFERENCES

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- **Prof. Deva Ramanan:** Professor, Robotics Institute, Carnegie Mellon University
- **Prof. Makarand Tapaswi:** Assistant Professor, Computer Vision Group, IIIT Hyderabad | Senior ML Scientist, Wadhvani AI
- **Prof. Nathaniel E. Chodosh:** Assistant Professor, Department of Computing Sciences, Villanova University
- **Prof. Saket Anand:** Associate Professor, IIIT Delhi.

## SERVICES

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- **Reviewer:** CVPR 2025, ECCV 2024, ICLR 2023
- **Mentorship @ CMU:** CMU AI Mentoring Program 2023
- **Mentorship @ Wadhvani AI :** Guided 2 interns for their projects on Uncertainty Estimation, Imbalanced Regression
- **Challenge Organizer:** Visual Perception and Learning in an Open World (**CVPR 2024**)
- **Invited Talks:** *AI Winter School*, IIIT-Delhi, 2019
- **Volunteering @ CSSAR NGO:** Taught basics of Science and English to students of classes 3-10.

## AWARDS AND ACHIEVEMENTS

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- **Dean's Award for Academic Excellence:** Excellent academic performance in a calendar year 2019
- **Technical Paper Award:** National Rank 1 for technical paper at **AUVSI-SUAS** competition 2017